

# Signals, systems, acoustics and the ear

Week 2

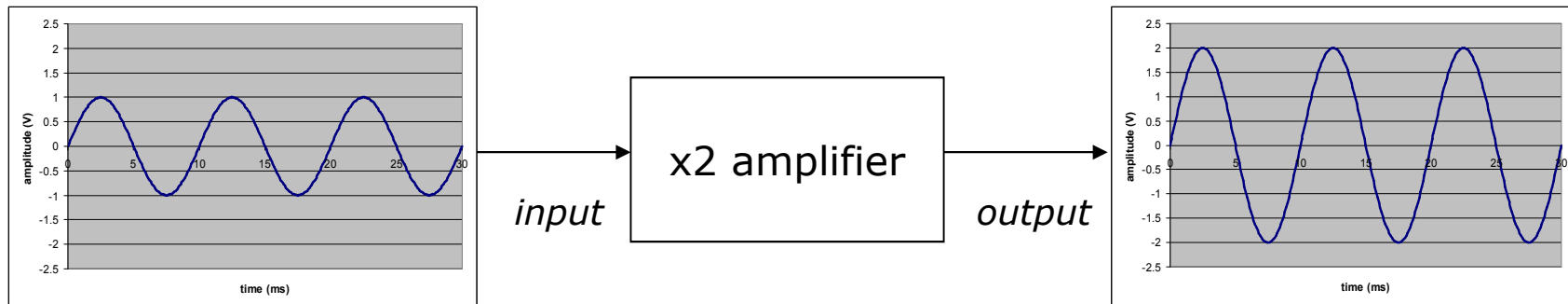
(Signals &) **Systems**  
&  
The ***Big*** idea



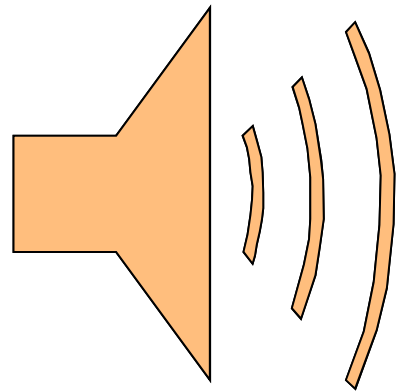
No eating or drinking in the lab!  
Not even water

# Reminder: What is a system?

- Something which performs an operation on, or transformation of, a signal
- For now, one input and one output



# A microphone (a special name for this kind of system?)



input = sound wave  
(variations in pressure)

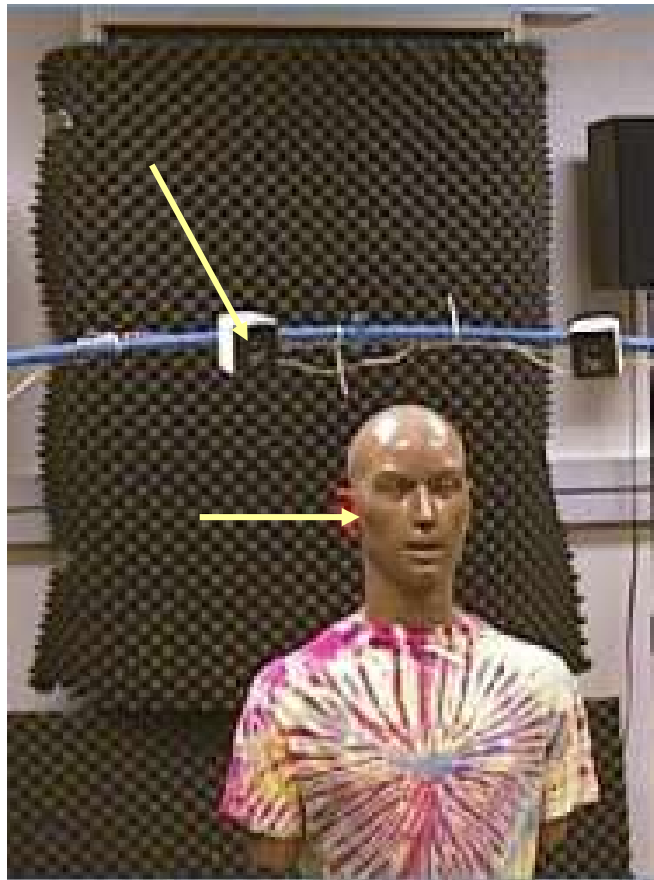


output =  
electrical wave  
(variations in  
voltage)



System = body + head +  
pinna + ear canal

input = sound  
from a  
particular place  
in space



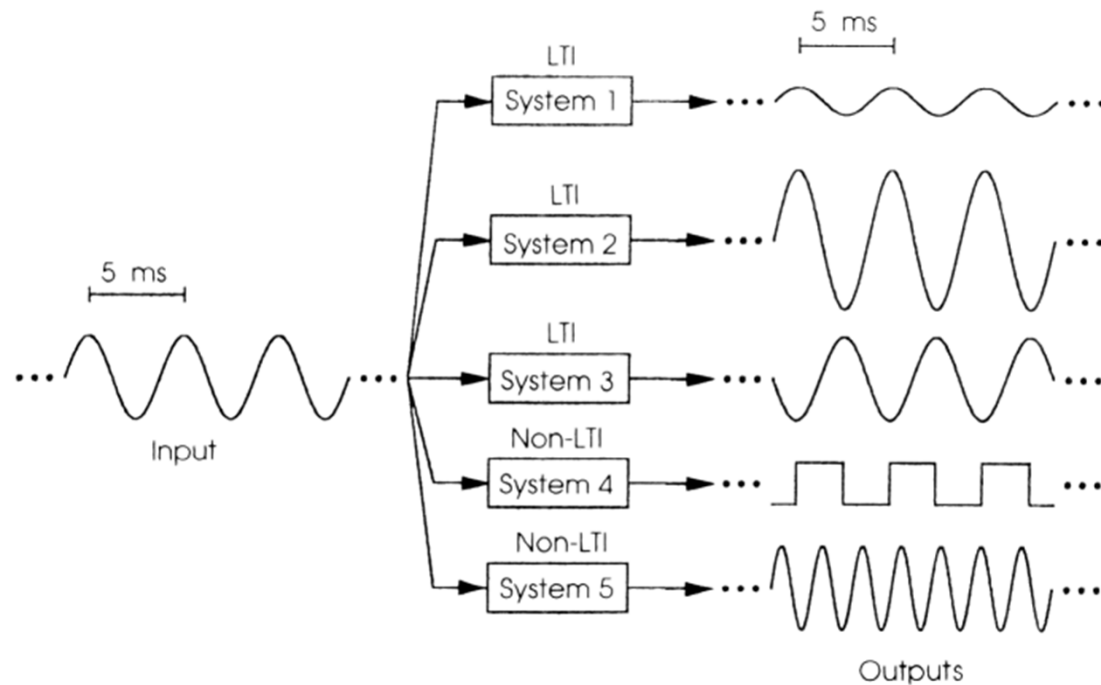
output =  
sound at the  
eardrum

# The problem

- We want to be able to predict what a system will do to a wide variety of signals, without having to try each one.
  - For example, speech from different people through a hearing aid
- No solution for *all* possible systems.
- It *is* possible for a group of very special systems, known as *linear time-invariant (LTI) systems*.

# Fact number 1

Sinusoidal input signals to an LTI system always lead to sinusoidal outputs of the **same frequency**



## Fact number 2

*An LTI system can be completely characterised by its response to sinusoids*



Today's Lab:  
Measuring the frequency  
response of an acoustic  
resonator

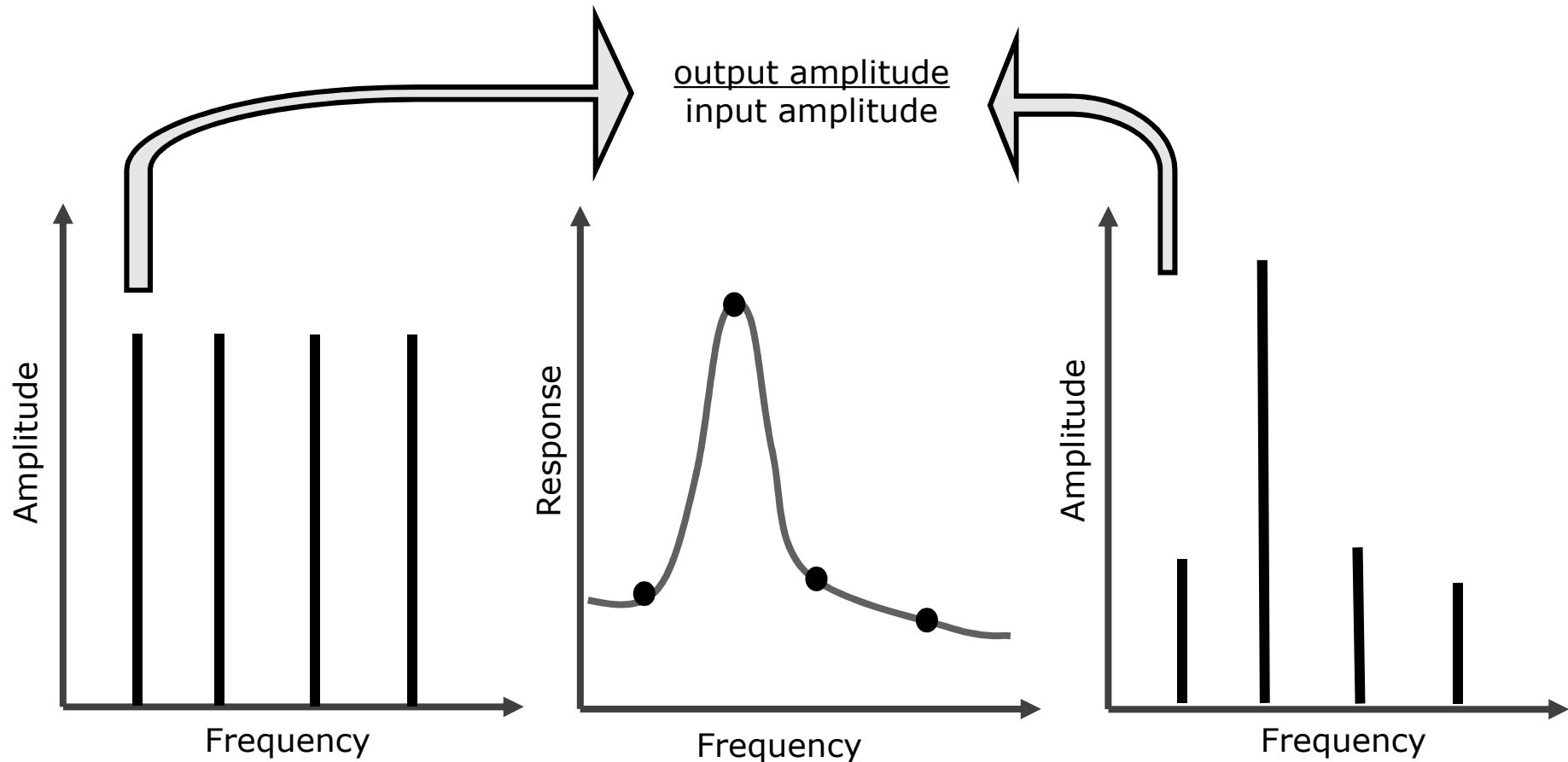
# Frequency response

- Also known as a *transfer function*
- Sinusoids vary on 3 parameters
  - frequency, amplitude & phase
- For a system, we need to specify its effect on two of those
  - amplitude response
  - phase response
- Amplitude response typically more important ...
  - but phase matters in certain situations
- So we will measure a so-called amplitude response.
  - How a system changes the amplitude of sinusoids
  - frequency response/transfer function/amplitude response

# Using sinusoids to measure an amplitude response in an LTI system

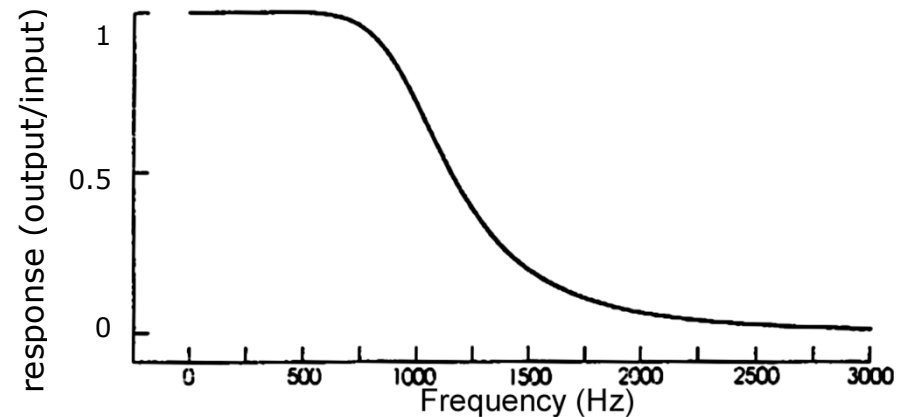
- Typically, choose a constant level for input (not necessary)
- For each frequency – feed the input sinusoid to the system and measure level at output
- Calculate the *response* = *output/input*
  - Also known as *gain*
- Need enough frequencies to map out amplitude response over frequency range of interest

# Characterisation of LTI-Systems



# At least 2 ways to specify a frequency response

frequency (Hz)	input (V)	output (V)	amplitude ratio (re 2V input)
250	2	2	1
500	2	1.98	0.99
1000	2	1.42	0.71
1500	2	0.56	0.28
2000	2	0.24	0.12
3000	2	0.08	0.04



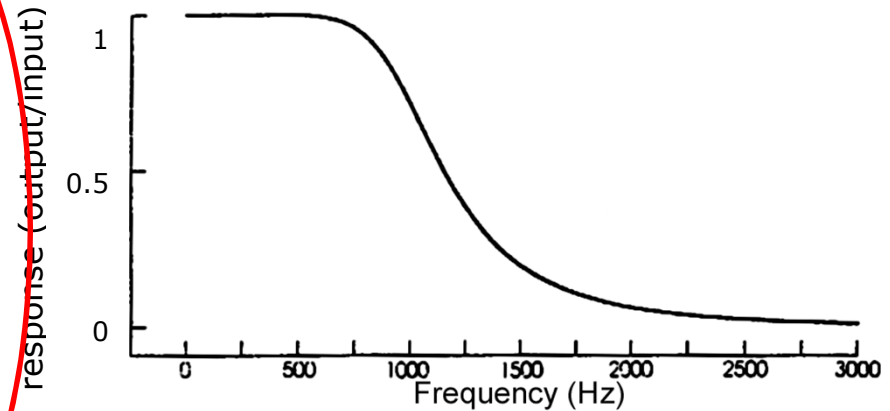
But easiest to see the overall effect on a graph, e.g. a low-pass response

# Scaling the response

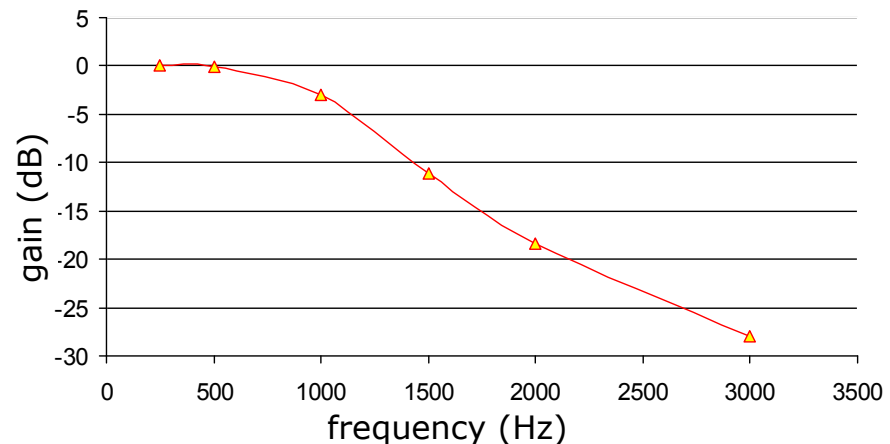
- Generally use a logarithmic scale for response (dB) rather than linear
- Amplitude ratio expressed in dB  
=  $20 \times \log(\text{output amp}/\text{input amp})$
- Note similarity to dB SPL  
–  $20 \log (? \text{ Pa}/20 \times 10^{-6} \text{ Pa})$
- Expresses output level in dB re input level

# At least 3 ways to specify a frequency response

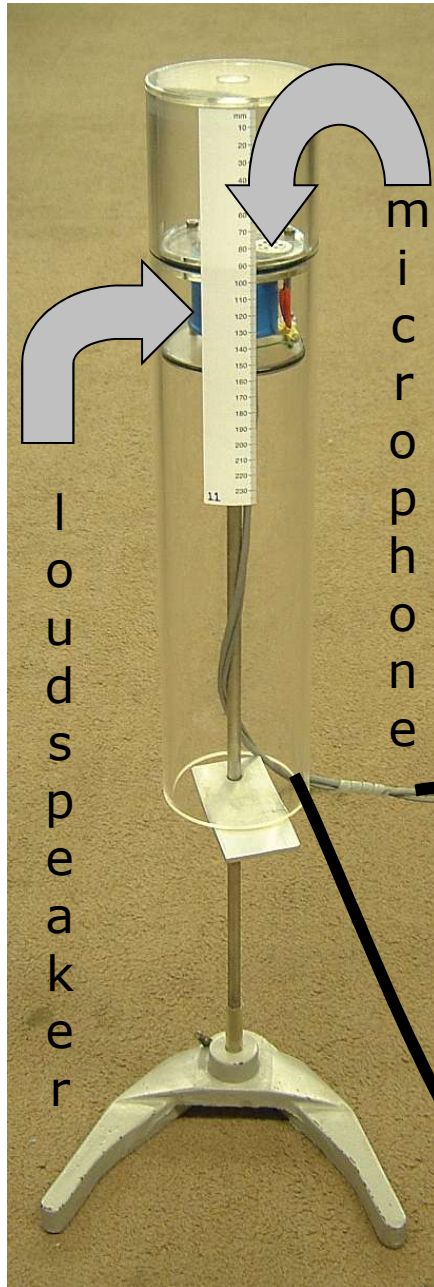
frequency (Hz)	input (V)	output (V)	amplitude ratio (re 2V input)	gain in dB
250	2	2	1	0.0
500	2	1.98	0.99	-0.1
1000	2	1.42	0.71	-3.0
1500	2	0.56	0.28	-11.1
2000	2	0.24	0.12	-18.4
3000	2	0.08	0.04	-28.0



But easiest to see the overall effect on a graph, e.g. a low-pass response



input = sinusoid from oscillator



output = sinusoid  
at a (probably)  
different level



**Battle stations everyone!**

# Linear Time-Invariant (LTI) Systems

Linearity = Homogeneity +  
Additivity

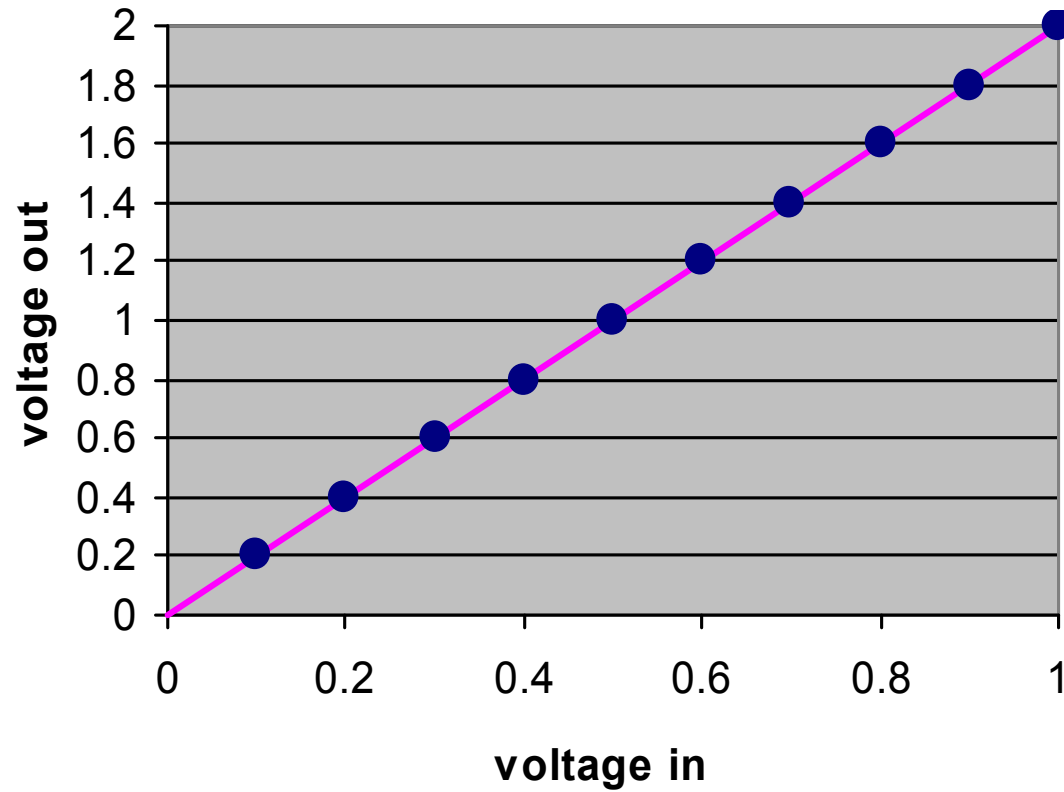
# Linearity in a system: Homogeneity

- Homogeneity
  - for a particular pair of input and output signals, any change in the size of the input signal is matched by the same change in the size of the output
  - If  $inp(t) \rightarrow outp(t)$
  - Then  $k \cdot inp(t) \rightarrow k \cdot outp(t)$
- In other words ...
  - Doubling the size of the input signal doubles the size of the output signal
  - Halving the size of the input signal halves the size of the output signal
- Nothing is implied about the relationship between the input and output waveforms!

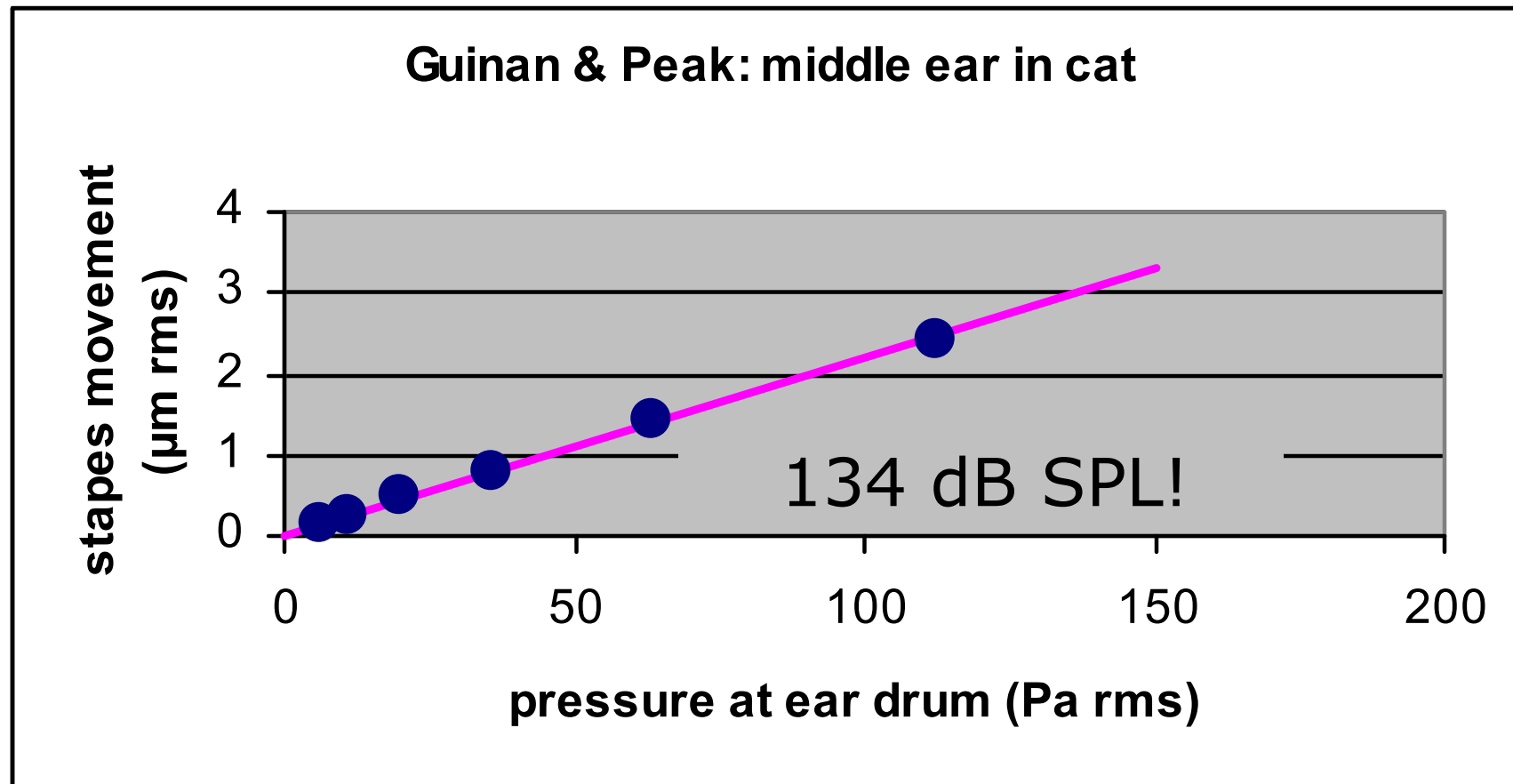
# A typical test of homogeneity

- Present a sinewave of a particular frequency to a system (but it can be *any* fixed sound)
- Measure the level of the output signal as you vary the level of the input signal
- Plot the level of the output signal on the y-axis and the level of the input signal on the x-axis
  - *input/output function*
- If the input/output function is a straight line going through the origin (0,0), that behaviour is consistent with homogeneity
- Any other kind of curve means the system is *not* homogeneous and hence, cannot be linear.
- Would our perfect x2 amplifier be homogeneous?

# An input/output function for a x2 amplifier

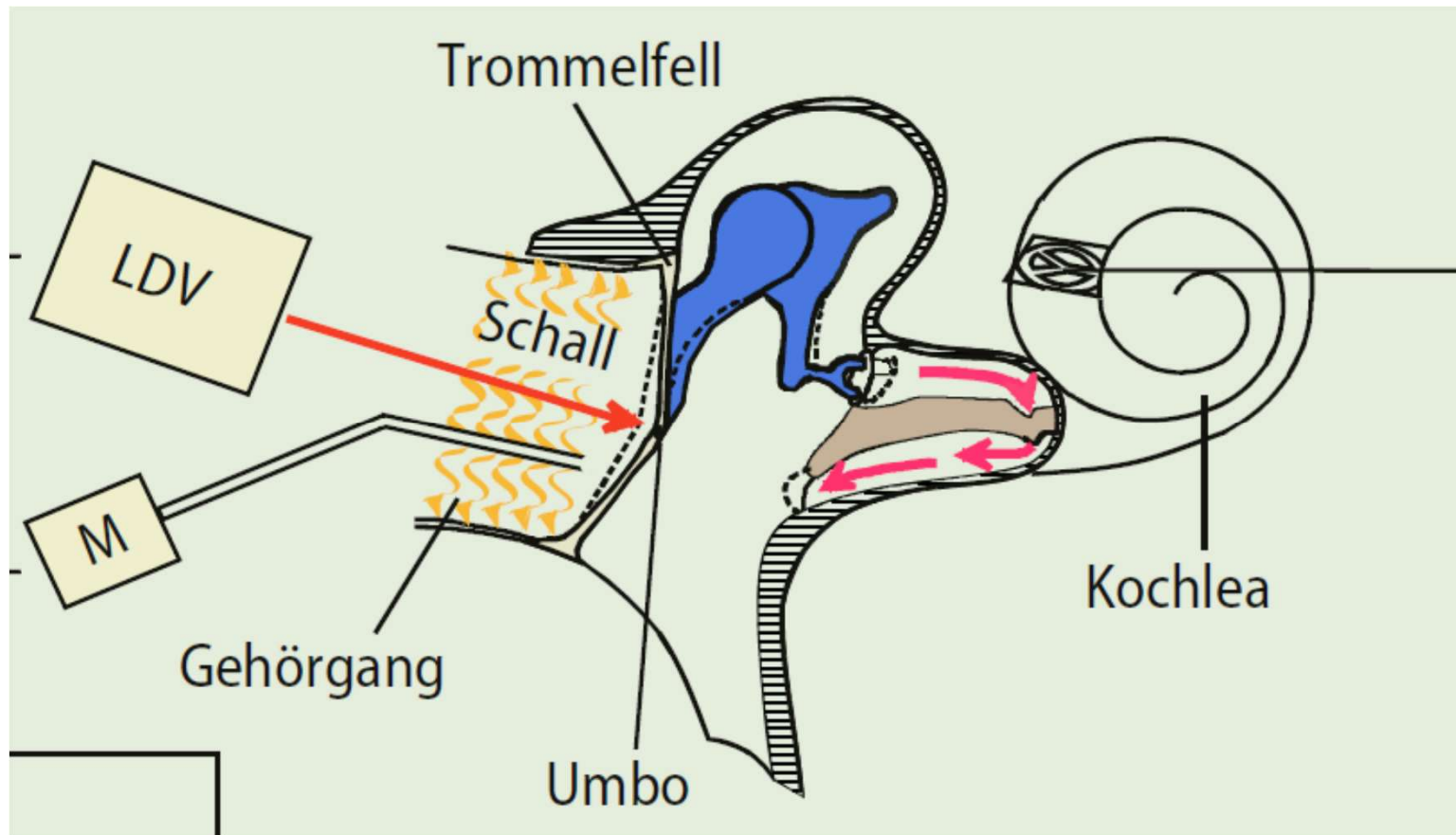


# Homogeneity in the cat middle ear

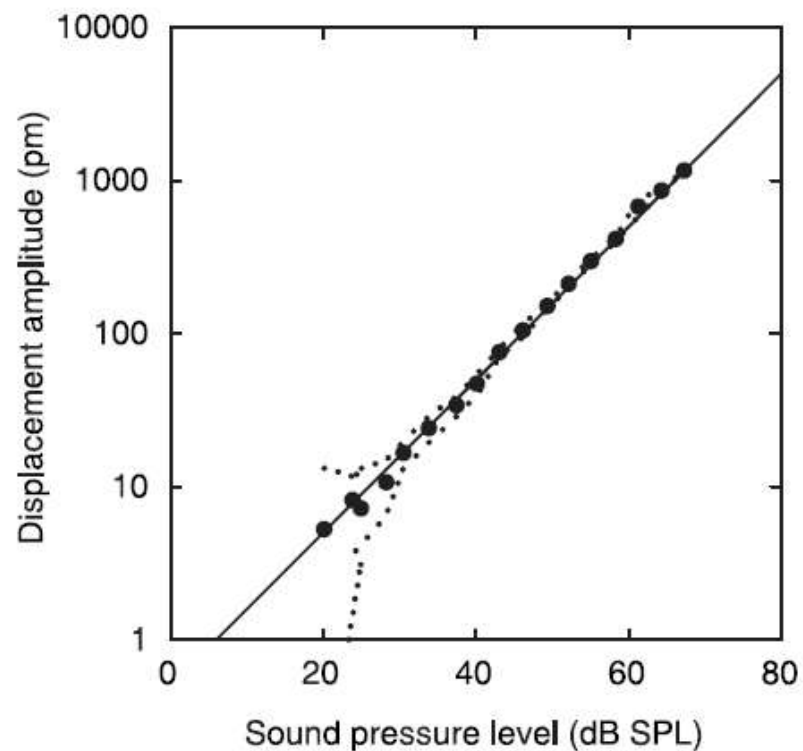


Would homogeneity hold at high levels?

# Laser Doppler Velocimetry of the human eardrum



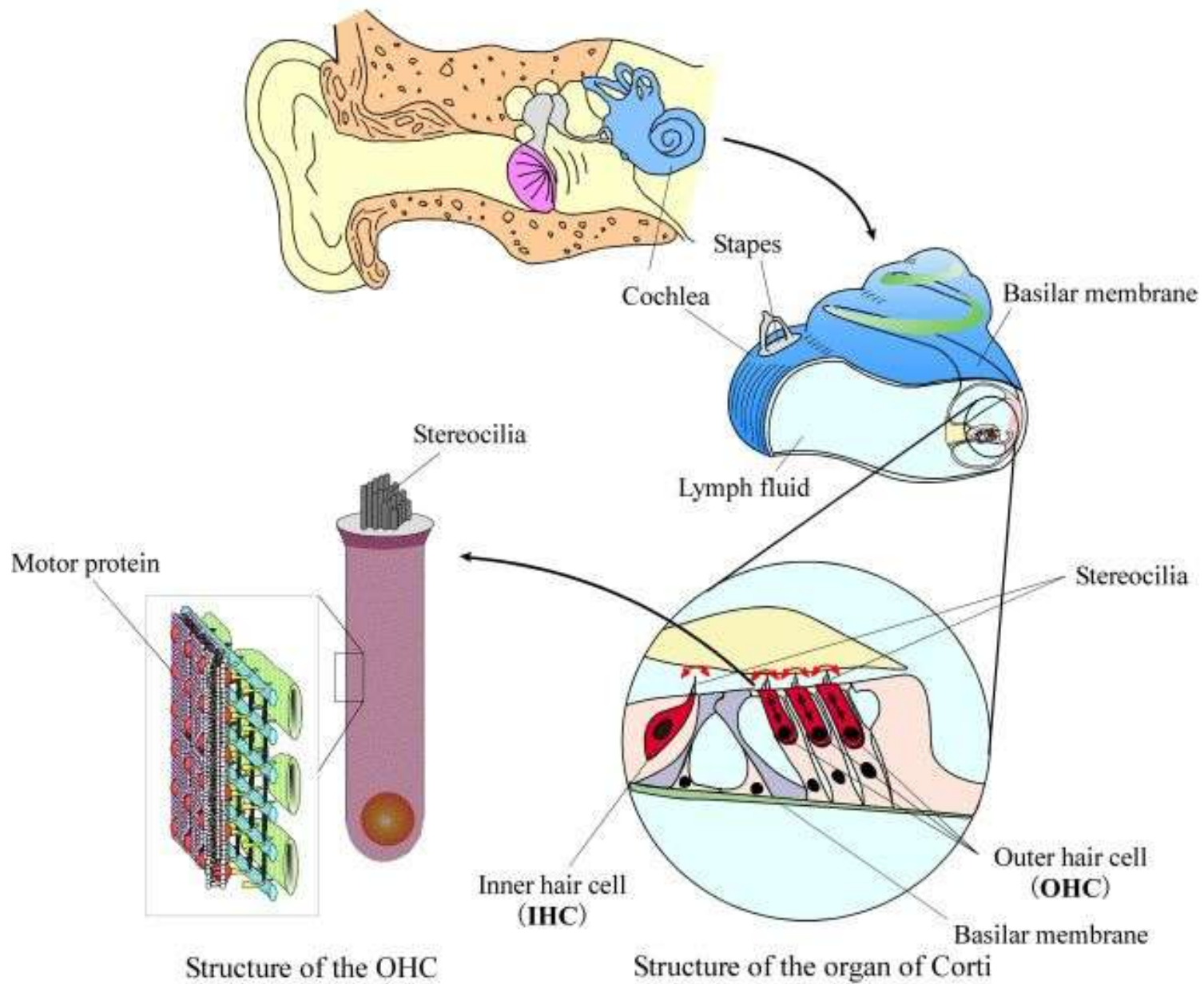
what kind of scale is this?



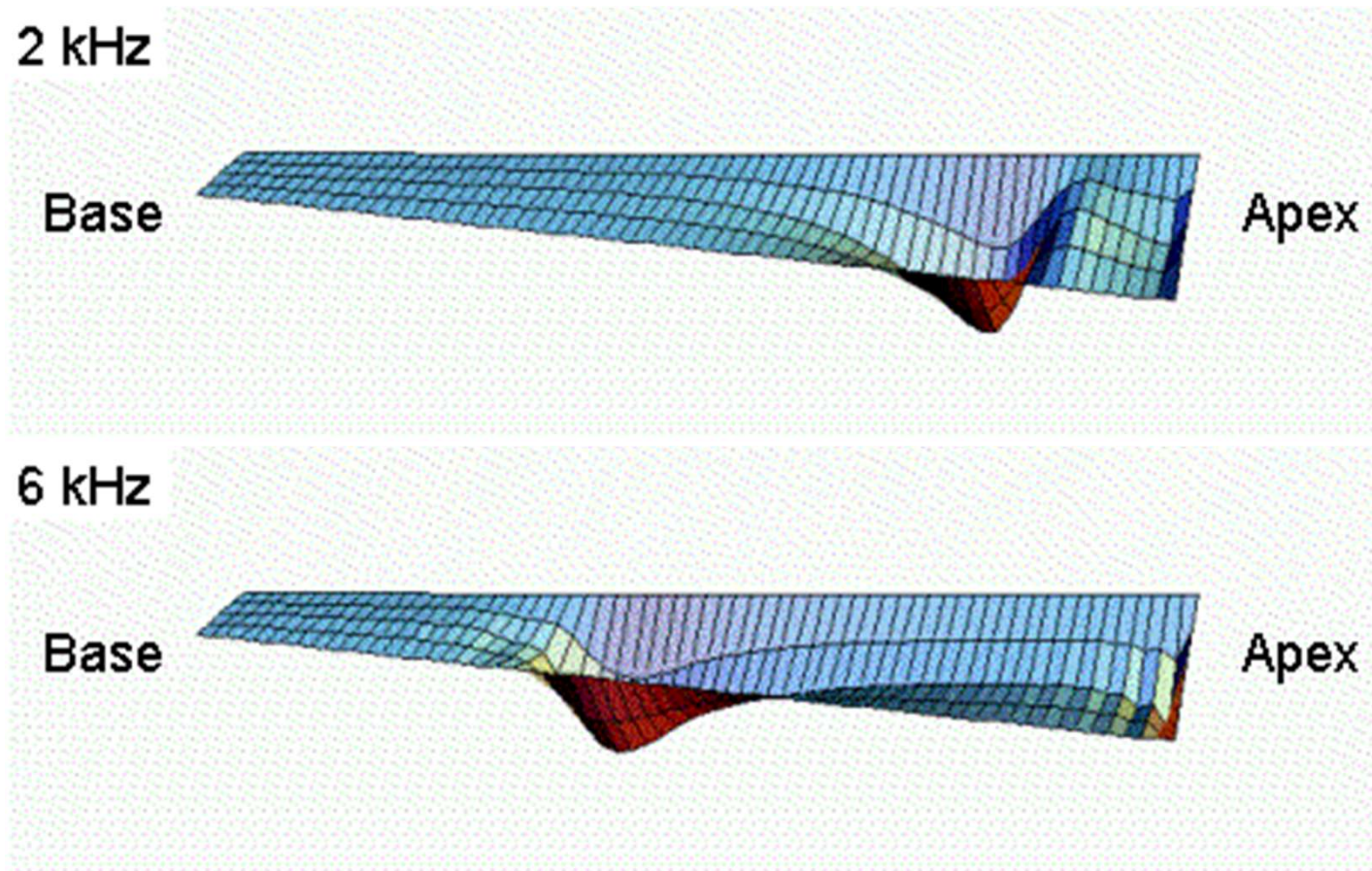
**Fig. 1.** Dependence of umbo displacement amplitude on SPL for single-tone stimulation (3.5 kHz) measured for an open sound field. The linear regression line of unity slope (1 dB/dB) indicates that the measured umbo response is linear. The dotted lines delineate the maximum noise level in the 100-Hz sidebands adjacent to the stimulus frequency. A reflector was not placed on the umbo. (Subject identifier: JT.)

Dalhoff et al. (2007) *PNAS* 104, 1546-1551

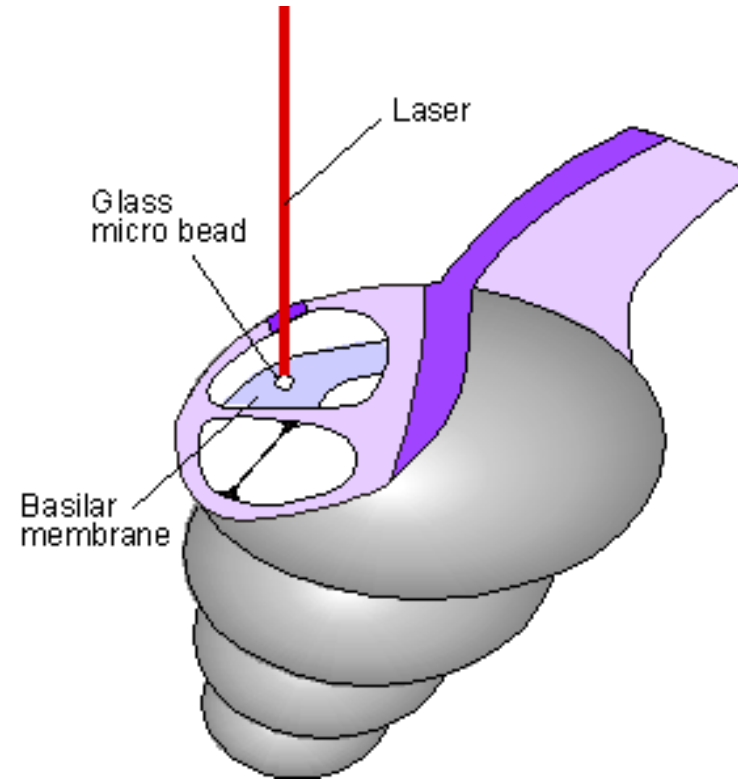
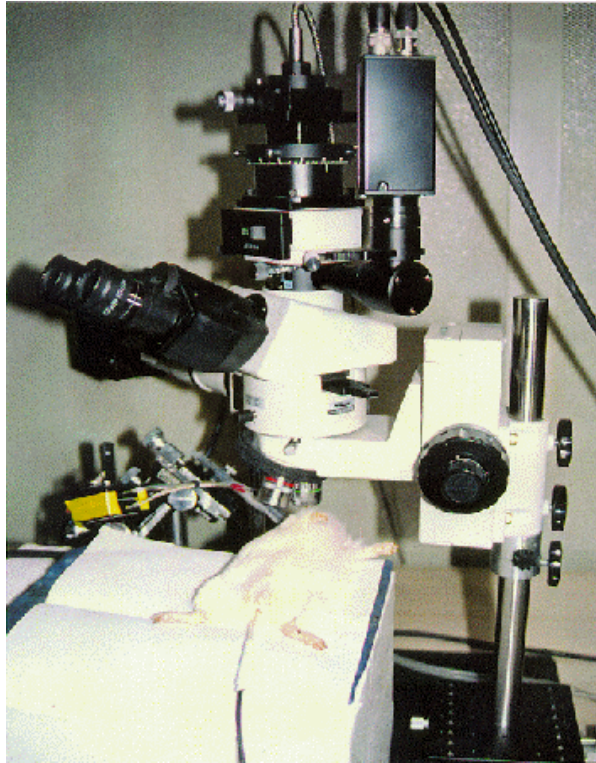




# Basilar membrane motion to two sinusoids of different frequency

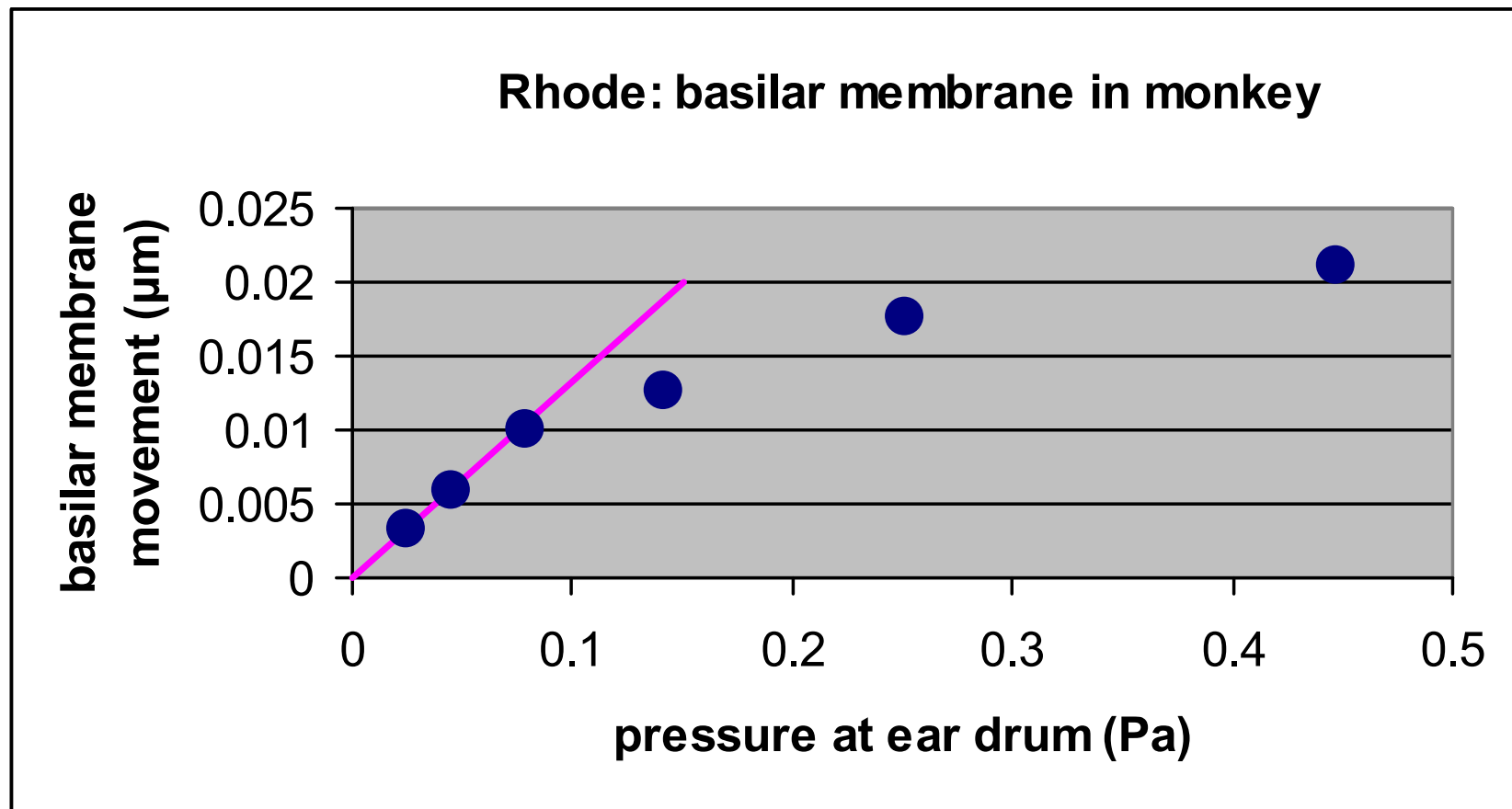


# Laser Doppler Velocimetry on the basilar membrane



<http://www.wadalab.mech.tohoku.ac.jp/bmldv-e.html>

# Homogeneity in the monkey inner ear?

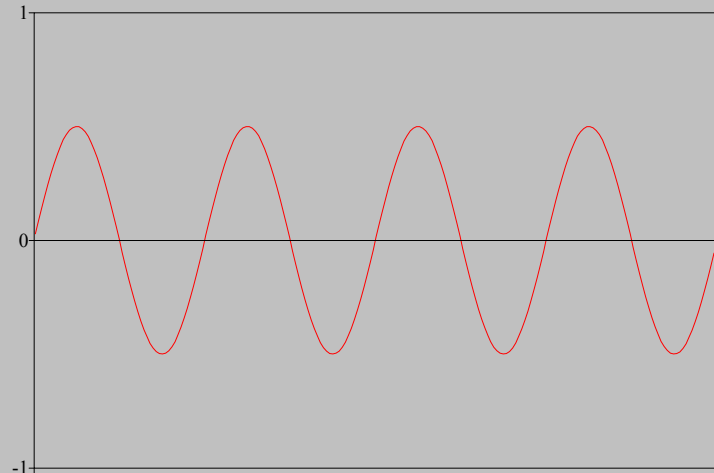


## Linearity Part II: Additivity

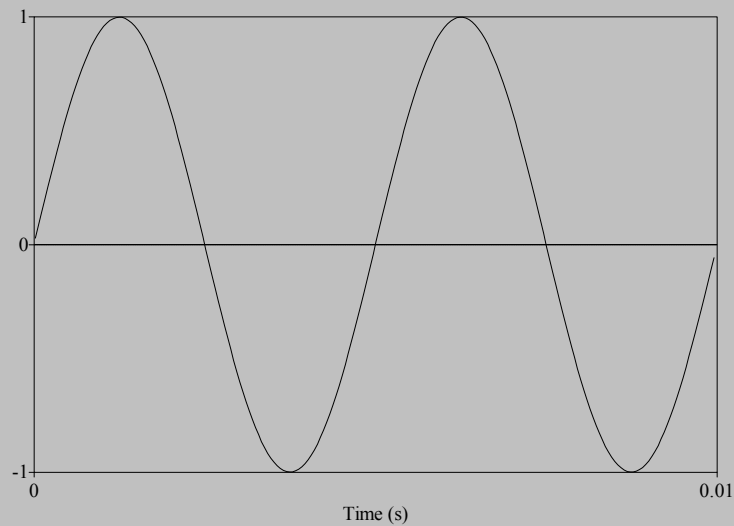
But first, what does it mean  
to add two waves?

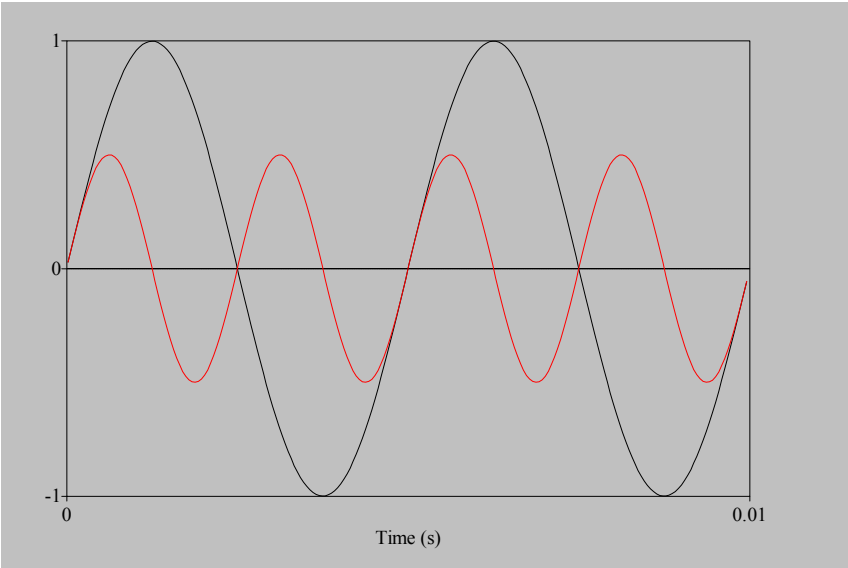
# Adding Waveforms

**400 Hz**  
 **$\frac{1}{2}$  V**

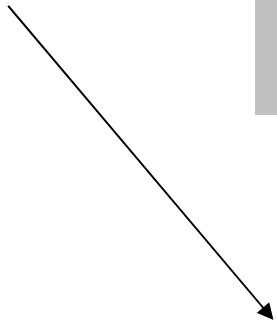
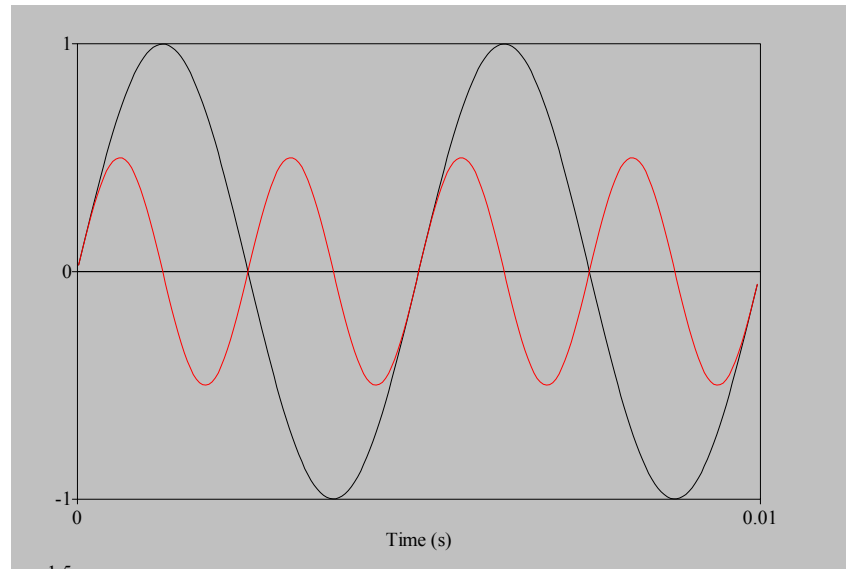


**200 Hz**  
**1 V**





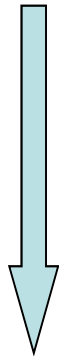
Adding up the two waveforms is performed by adding the amplitude values at each point in time.



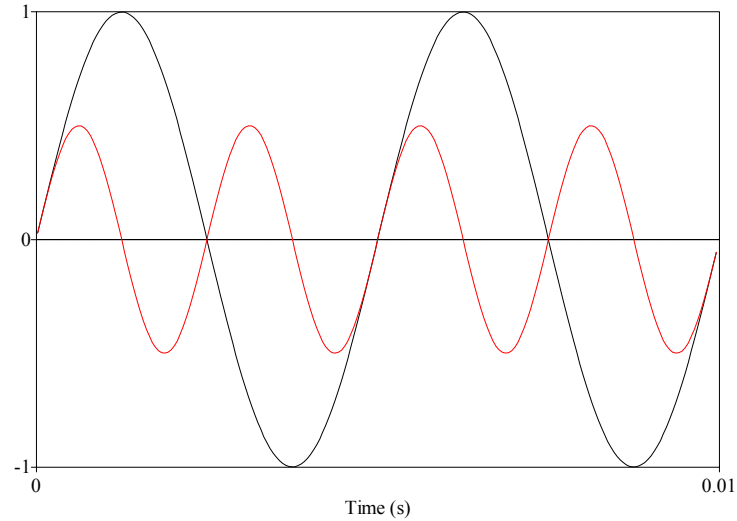


# Adding Waveforms

**sinusoids**

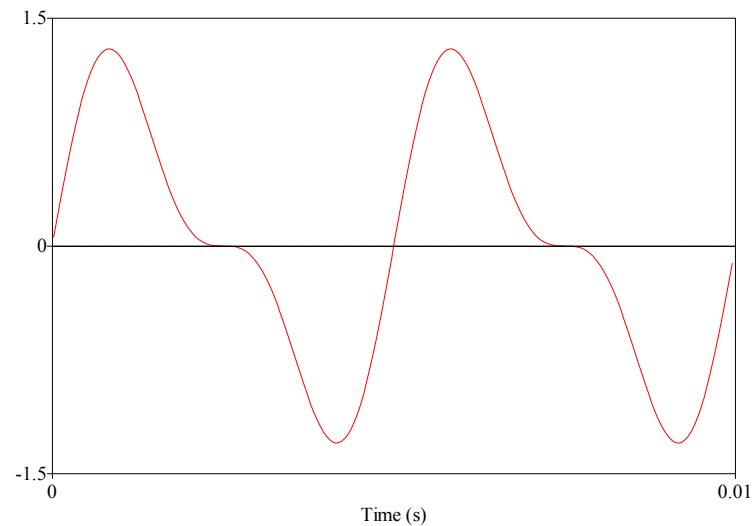



**complex waveform**



 200 Hz

 400 Hz

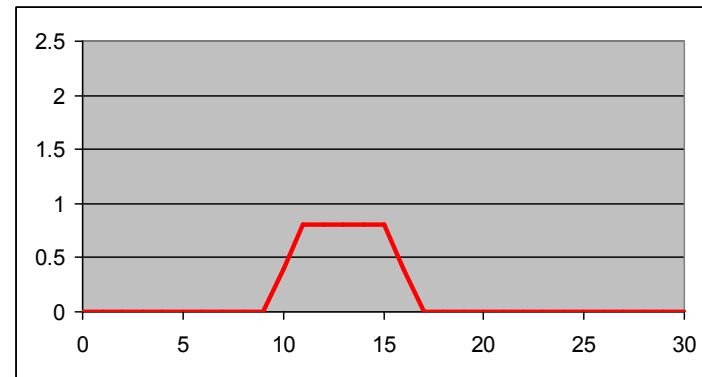
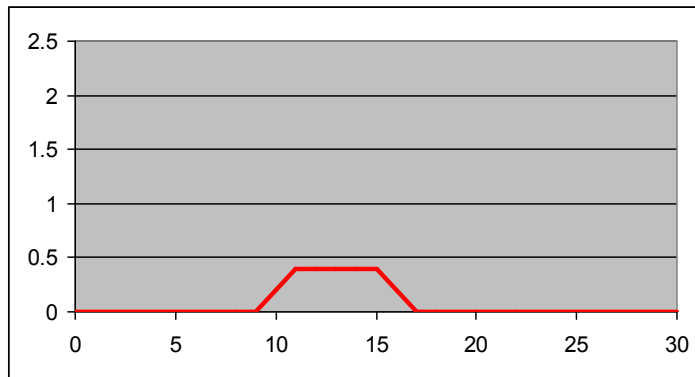
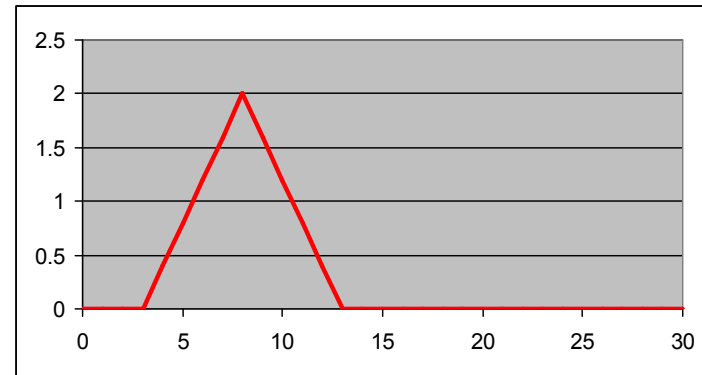
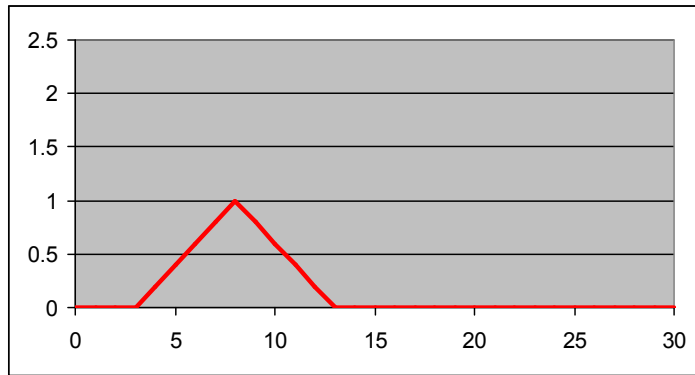


 200+400 Hz

# Linearity in a system: Additivity

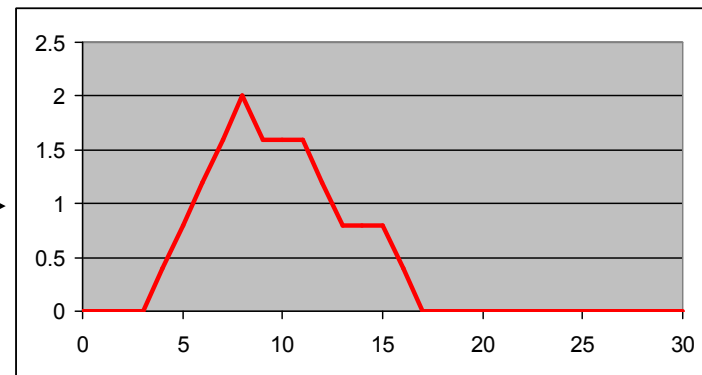
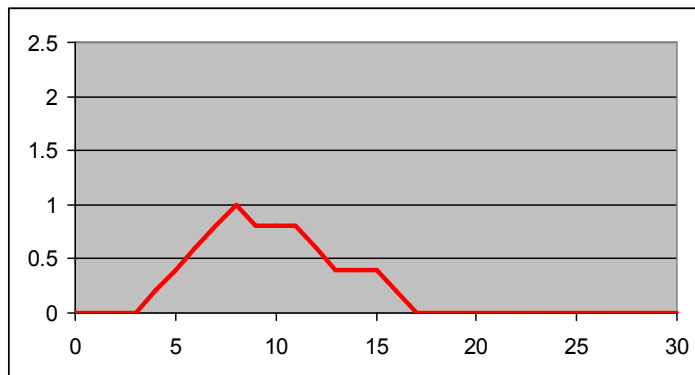
- Additivity (principle of superposition)
- The output of a system to two input signals added together, is the same as the separate output signals for each of the inputs on their own, added together.
- In other words, signals don't interact.
- In simple equations:
  - If  $inp_1(t) \rightarrow outp_1(t)$  &  $inp_2(t) \rightarrow outp_2(t)$
  - Then  $inp_1(t) + inp_2(t) \rightarrow outp_1(t) + outp_2(t)$

# Additivity: A simple example



+

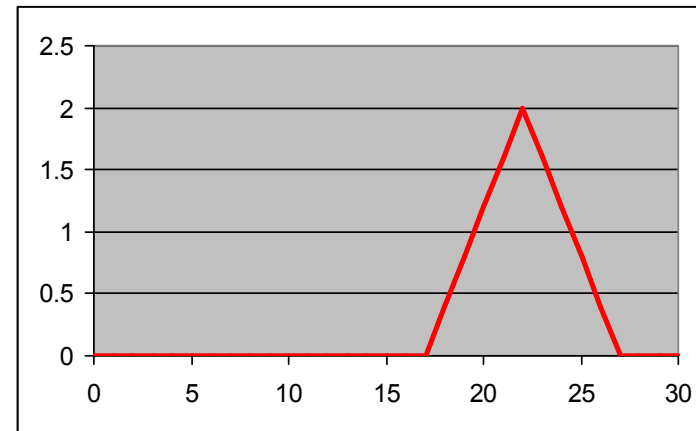
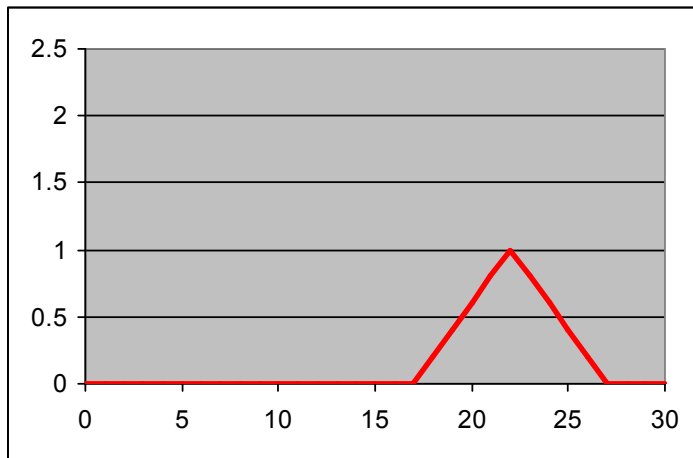
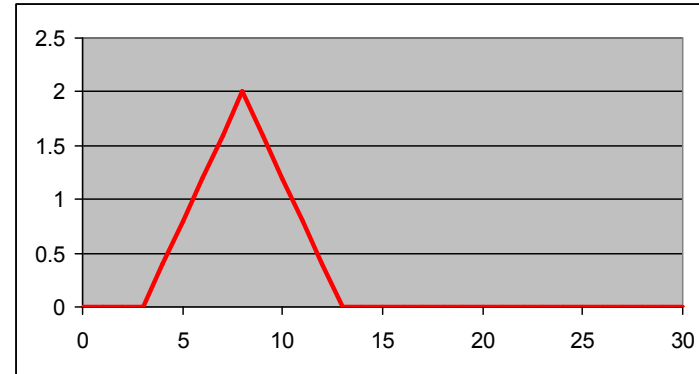
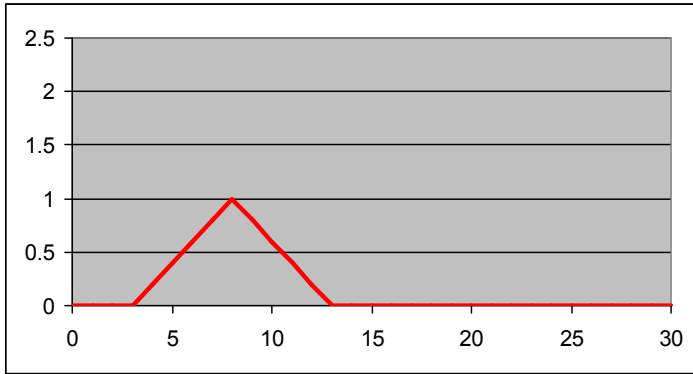
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# Requirement 3: Time-invariance

- For a particular pair of input and output signals, delaying the input signal by a particular amount also delays the output signal by the same amount.
- The system's behavior does not change in time

# Time invariance: A simple example



# Our goal

*To characterise the  
behaviour of a system that  
allows us to predict the  
output of the system to any  
input signal*

# Our motto

*We don't care how a system changes a signal, we only care for what the system does to the signal, so ...*

*We don't study the system itself but we compare the output to the input.*

# LTI systems are...

## ... linear

- Homogeneity
  - The amplitude of output signals grows proportionally with the amplitude of input signals, with no change in the *shape* of the output
- Additivity
  - The output to the sum of two input signals is the sum of the outputs to the two inputs separately
  - Signals don't interact

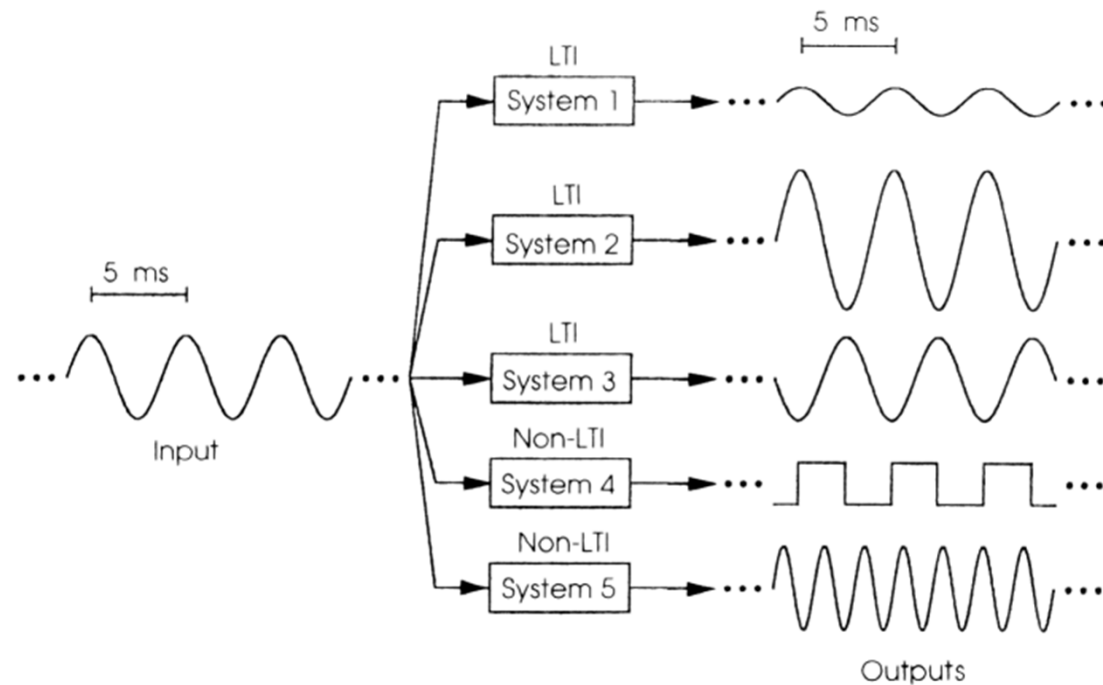
## ... time-invariant

- What a system does to an input signal today, is the same as what it will do tomorrow
- The system does not change its behaviour over time

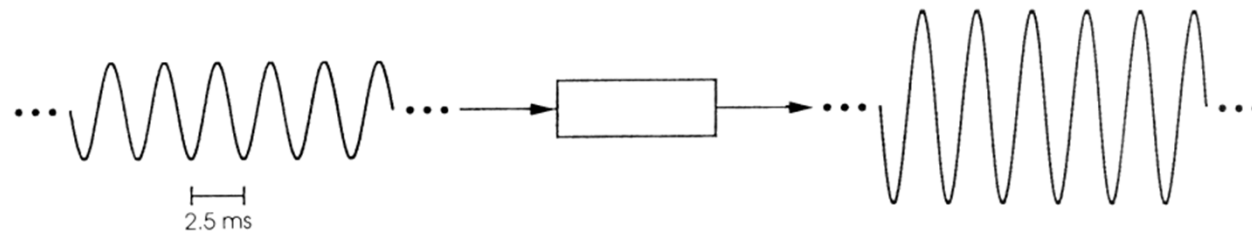
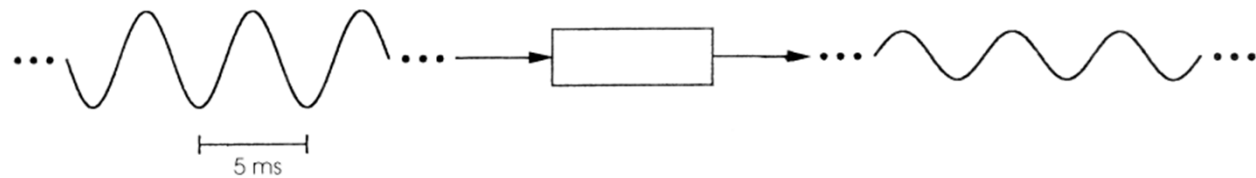


*An LTI system can be  
completely characterised  
by its response to  
sinusoids*

Sinusoidal input signals to an LTI system always lead to sinusoidal outputs of the **same frequency**

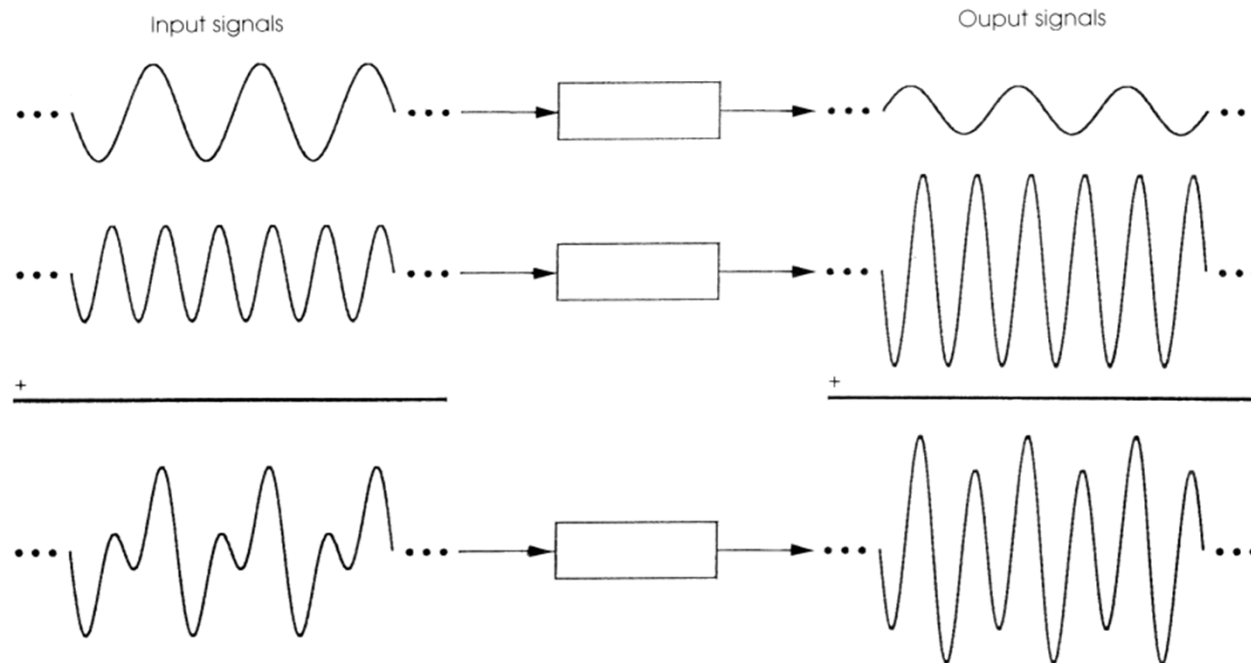


Knowing the response of a system to a sinusoid of a particular frequency, amplitude and phase allows the prediction of the output of the system to a sinusoid of the same frequency, but any amplitude and any phase



Why?

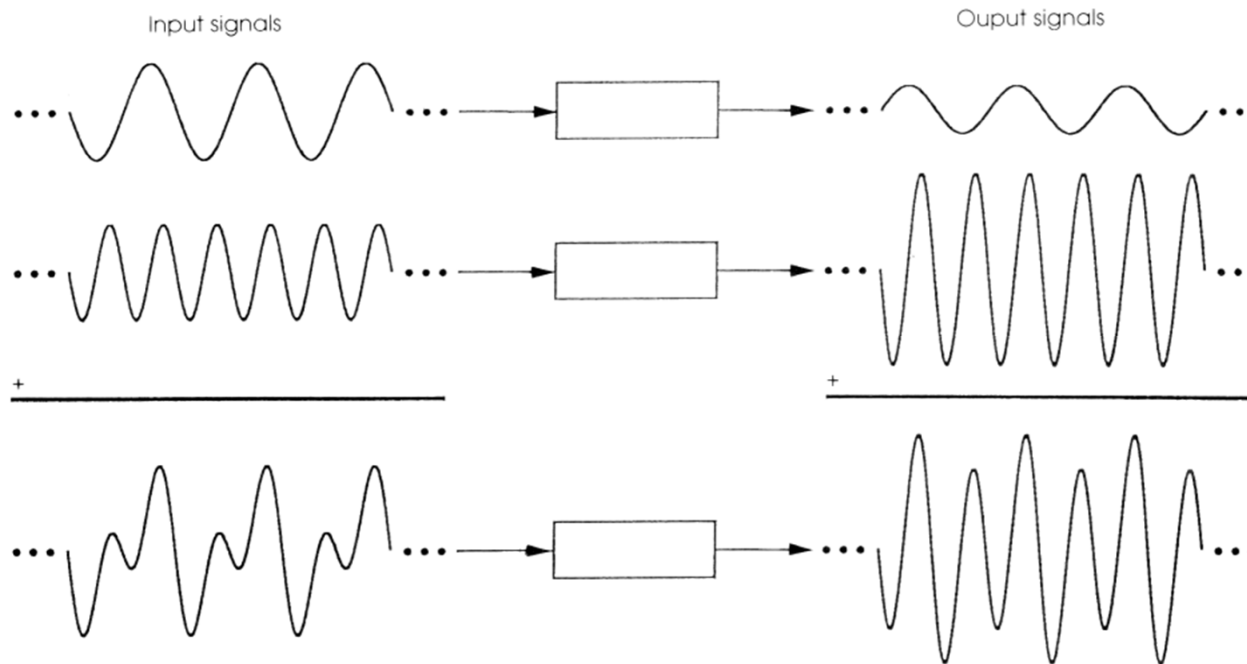
Knowing the response of a system to any frequency sinusoid allows the prediction of the output of the system to any signal that can be made from adding up sinusoids of *any* frequency, amplitude and phase



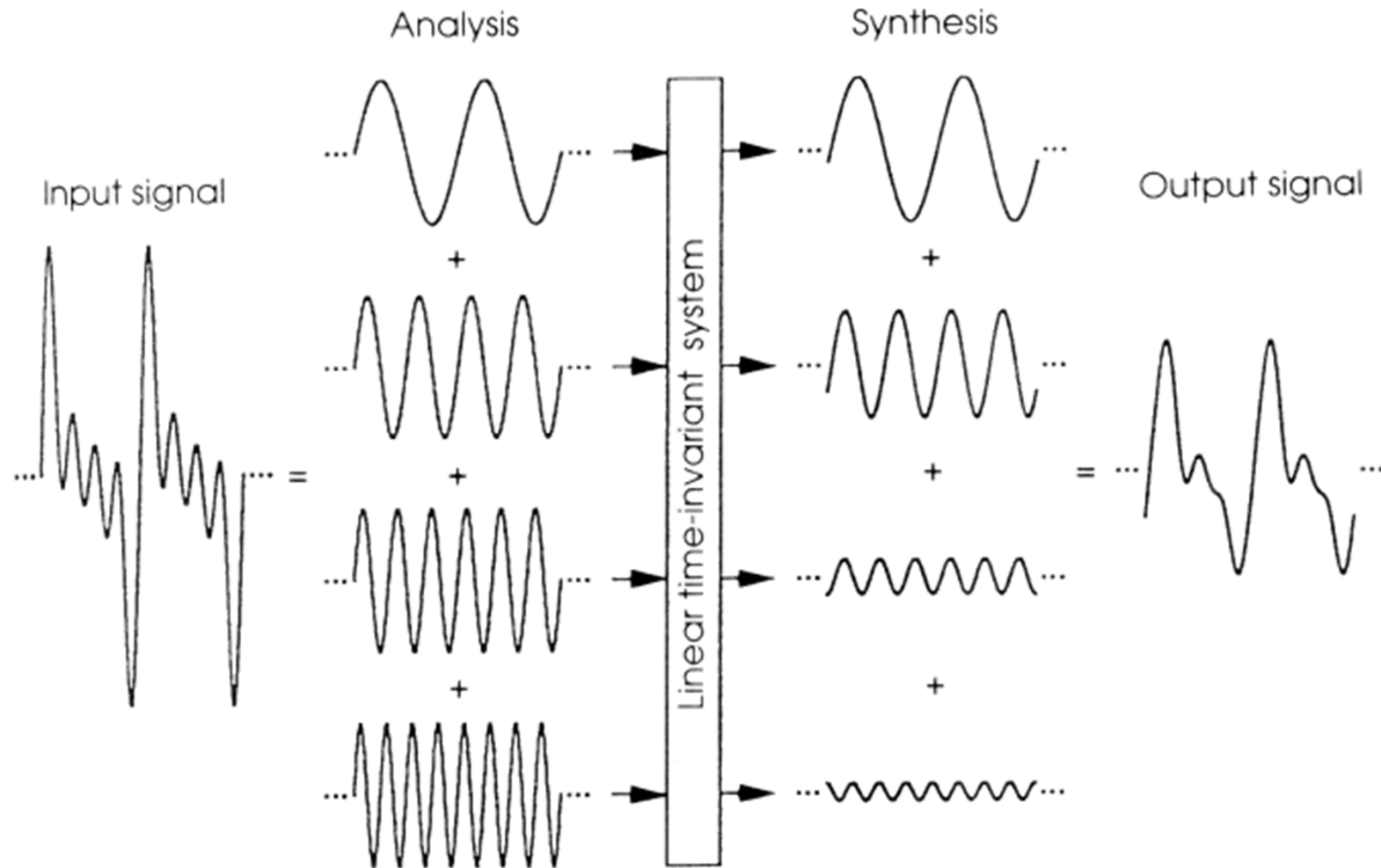
Why?

# Fact number 3

Any complex wave can be made by adding up sinusoids of varying frequency, amplitude and phase



# The **BIG** idea: Illustrated



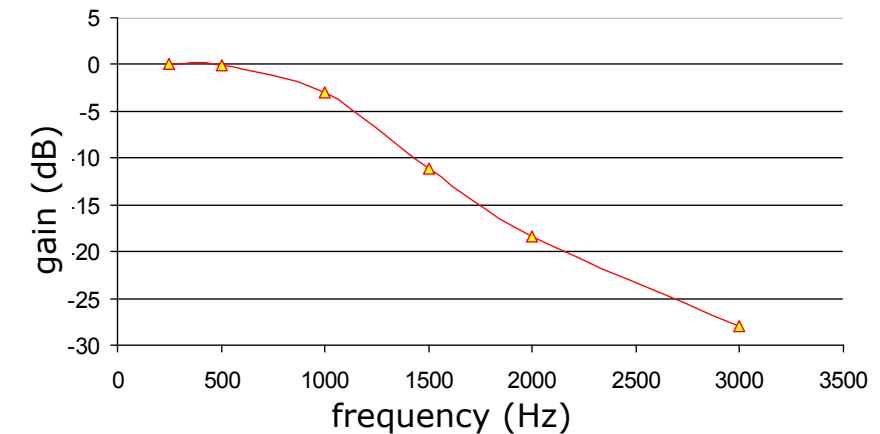
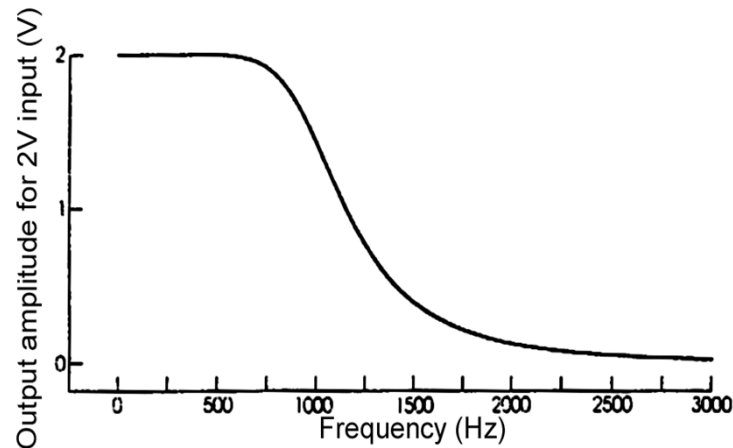
# Physical systems react differently to different frequencies

- A swing or pendulum
- Acoustic resonators
- Mass on a spring
- Bridges

Tacoma Narrows Bridge Collapse.wmv



# Amplitude Response: Key points



- The change made by a system to the amplitude of a sinewave, specified over a range of frequencies.
- Response = output amplitude/input amplitude
- Usually scaled in dB as:  
 $20 \times \log(\text{output amplitude}/\text{input amplitude})$   
= response (dB re input amplitude)



# Once we have a frequency response

- We can calculate the output for any given sinusoidal input
- For any particular frequency, we know that
  - $response_f = output\ amplitude_f / input\ amplitude_f$
- So that
  - $output\ amplitude_f = response_f \times input\ amplitude_f$
- Why is this valid?